

Elektrodynamik-Tutorium

Mitgeschrieben und geLATExt von Julian Bergmann

Inhaltsverzeichnis

1	29.10.10	1
1.1	Partielle Integration	1
1.2	δ -Funktion	1
1.3	Beispiele	1
2	5.11.10	2
2.1	Integral-Grenzwerte	2
2.2	Beispiele	2
2.3	Satz von Gauß	3
3	12.11.10	3
3.1	Beispiele	3
3.2	Fortsetzung: Halbkugel mit $R=1$	3
3.3	Koordinatensysteme	4
3.4	Beispiel: parabolische Koordinaten	4
3.5	Ladungsverteilung Draht	4
3.6	Ladungsverteilung Kugelschale	5
4	19.11.10	5
4.1	Integrale	5
4.2	Fortsetzung E-Feld Kugelschale	5
4.3	Poisson-Gleichungen	5
4.4	Fourier	6
5	26.11.10	6
5.1	Kugelfunktion	6
5.2	Integrale	6
5.3	Hausaufgabenhinweise	6
5.4	geerdete Kugel	7
6	3.12.10	7
6.1	Anwendung Nabla in Kugelkoord	7
6.2	Beispiel: ungeladene Metallkugel	8
6.3	Kugel mit Oberflächen-Ladung	9
7	21.1.11	9
7.1	Magnetfelder	9
7.2	Induktionsgesetz	9
7.3	Beispiel: Leiterschleife durch Magnetfeld	9
7.4	Maxwell-Gleichungen	10

7.5	em-Wellen im Vakuum	10
7.6	Lösung d. Wellengleichung	10
7.7	Eigenschaften von em-Wellen	10
8	28.1.11	11
8.1	Wellengleichung	11
8.2	Fourier-Transformation	11
9	11.2.11	12
9.1	Aufgabe 1	12
9.2	Aufgabe 2	12
9.3	Aufgabe 3: 3-Dim Fouriertransf.	13
9.4	linearer, homogener, aufgeladener Isolator	13
10	18.2.11	13
10.1	Biot-Savart	13
10.2	Magnetfeld	14
10.3	Schwingkreis	15
10.4	Wellenpakete	15
10.5	Energie-/Energiestromdichte	15
10.6	Brechung/Reflexion	15
10.7	Blatt 13, NR.3	15

1 Elektrodynamik Tutorium vom 29.10.2010

1.1 Partielle Integration

a) $-\frac{d}{dx}e^{-x^2+1} = 2xe^{-x^2+1}$
 $\int_0^\infty 2xe^{-x^2+1}dx = [e^{-x^2+1}]_0^\infty = -(0 - e) = e$

b) $\int_a^b xe^{-5x}dx = [-\frac{1}{5}e^{-5x}]_a^b - \int_a^b -\frac{1}{5}e^{-5x}dx$

c) $\int_0^\infty x^n e^{-ax}dx = \frac{n!}{a^{n+1}}$
 $= \underbrace{[-\frac{1}{a}e^{-ax}x^n]_0^\infty}_{=0} - \int_0^\infty nx^{n-1}(-\frac{1}{a})e^{-ax}dx = \int_0^\infty \frac{n}{a}e^{-ax}x^{n-1}dx$
 $= \int_0^\infty \frac{n!}{a^n}e^{-ax}dx + [(-\frac{1}{a})^n e^{-ax}x]_0^\infty = [-\frac{n!}{a^{n-1}}e^{-ax}]_0^\infty = 0 + \frac{n!}{a^{n+1}}$

1.2 δ-Funktion

- $\int_\alpha^\beta f(x)\delta(x-a)dx = f(a) \quad \forall \alpha < a < \beta$
- $f(x)\delta'(x-a) = -f'(x)\delta(x-a)$
- $\delta(f(x)) = \sum_i \frac{1}{|f^{-1}(x_i)|}\delta(x-x_i), \quad x_i \text{ NS von } f(x)$

Bsp.: $x^2 - 3x + 2 = 0 \Rightarrow x = \{1, 2\}$

$$f'(x) = 2x - 3, \quad f'(x_1) = 2 - 3 = -1, \quad f'(x_2) = 4 - 3 = 1$$

$$\int_0^\infty x^2 \delta(x^2 - 3x + 2)dx = \int_0^\infty (\frac{1}{|-1|}x^2 \delta(x-1) + \frac{1}{|1|}x^2 \delta(x-2))dx = 1 + 4 = 5$$

Beispiele: $\int_{-\infty}^{+\infty} dx(x^2 + 7x)\delta(x-x_0) = x_0^2 + 7x_0$

Behauptung: $\delta(\vec{r} - \vec{r}') = \frac{1}{4\pi} \Delta_r \frac{1}{|\vec{r} - \vec{r}'|}$, Beweis:Nolting

Beweisskizze: Es muss gelten $\delta(x-a) = 0, \quad \forall a \neq x$ und $\int_\alpha^\beta dx \delta(x-a) = 1$

$\Delta_r = \vec{\nabla}_r \cdot \vec{\nabla}_r, \quad \vec{\nabla} \vec{A} = 0 \Rightarrow \text{Quellenfrei}, \quad \vec{\nabla} \times \vec{A} = 0 \Rightarrow \text{Wirbelfrei}$

1.3 Beispiele

a) $\int_0^1 \sqrt{1-x^2}dx, \quad x = \sin(t), \quad dx = \cos(t)dt$
 $\Rightarrow \int_{\arcsin(0)}^{\arcsin(1)} \sqrt{1-\sin^2(t)} \cos(t)dt = \int_0^{\pi/2} \sqrt{\cos^2(t)} \cos(t)dt = \int_0^{\pi/2} \cos^2(t)dt$
 $\cos^2(t) = \frac{1+\cos(2t)}{2} \Rightarrow \dots = [\frac{x}{2} + \frac{1}{4}\sin(2x)]_0^{\pi/2} = \frac{\pi}{4}$

b) $\int_0^2 x \cos(x^2 + 1)dx, \quad t = x^2 + 1, \quad 2xdx = dt$

$$\dots = \int_1^5 \frac{1}{2} \cos(t)dt = \frac{1}{2}[\sin(t)]_1^5$$

2 Elektrodynamik Tutorium vom 5.11.2010

2.1 Integral-Grenzwerte

- $\int_0^\infty x^2 e^{-2x} dx = [(-\frac{1}{2}x^2 - \frac{1}{2}x - \frac{1}{4})e^{-2x}]_0^\infty = 0 + \frac{1}{4}$
- $\int_0^\infty x^2 e^{-2x} dx = \frac{n!}{a^{n+1}} = \frac{1}{4}$
- $\int_1^\infty xe^{x^2+1} dx, \quad t = x^2 - 1$
 $\Rightarrow \dots = \int_0^\infty \frac{x}{2x} e^{-t} dt = \frac{1}{2} \int_0^\infty e^{-t} dt = \frac{1}{2}$
- $\int_{-\infty}^\infty (3x^2 + 5x)\delta(x-3)dx = (3x^2 + 5x)|_{x=3} = 42$
- $\int_{-5}^5 (x^2 + x)\delta(2x^2 - 4x - 6)dx$
 $0 = 2x^2 - 4x - 6 \Rightarrow x_1 = -1, x_2 = 3$
 $f'(x) = 4x - 4, f'(x_1) = 8, f'(x_2) = -8$
 $\Rightarrow \dots = \int_{-5}^5 \frac{1}{8}(x^2 + x)(\delta(x-3) + \delta(x+1))dx = \frac{12}{8}$

2.2 Beispiele

$$\begin{aligned}
 r &:= \sqrt{a^2 + b^2 + c^2} \\
 |\vec{a} - \vec{b}| &= \sqrt{a^2 + b^2 - 2ab \cos(\theta)} \\
 \varphi(r+r') \text{ um r: } \varphi(r+r') &= \varphi(x_1 + x'_1, x_2 + x'_2, x_3 + x'_3) = F(t=1) \\
 F(t) &= \varphi(x_1 + x'_1 t, x_2 + x'_2 t, x_3 + x'_3 t) \\
 F(t) &= \sum_{n=0}^{\infty} \frac{1}{n!} F^{(n)}(0) t^n \text{ um } t=0 \\
 F'(0) &= \sum_{j=1}^3 \frac{\partial \varphi}{\partial x_j} x_j \\
 F''(0) &= \sum_{jk} x'_j x'_k \frac{\partial^2}{\partial x_k \partial x_j} \varphi(r) = \left(\sum_j \frac{\partial}{\partial x_j} \right)^2 \varphi(r) \\
 F^{(n)}(0) &= \left(\sum_j \frac{\partial}{\partial x_j} \right)^n \varphi(r) \\
 F(t=1) &= \varphi(r+r') = \sum_{n=0}^{\infty} \frac{1}{n!} \left(\sum_j x_j \frac{\partial}{\partial x_j} \right)^n \varphi(r)
 \end{aligned}$$

Beispiel:

$$\begin{aligned}
 \varphi(r) &= \frac{\alpha}{|r-r_0|} \text{ um } r=0 \text{ entwickeln:} \\
 n=0: \quad \varphi(r)|_{r=0} &= \frac{\alpha}{r_0}, r_0 > 0 \\
 n=1: \quad \sum_{j=1}^3 x_j \frac{\partial}{\partial x_j} \varphi(r)|_{r=0} &= \sum_{j=1}^3 x_j \frac{\partial}{\partial x_j} \left(\frac{\alpha}{|r-r_0|} \right)|_{r=0} = \sum_{j=1}^3 x_j x_j (j_0) \frac{\alpha}{r_0^3} \\
 n=2: \quad \sum_{j,k} x_j x_k \frac{\partial^2}{\partial x_k \partial x_j} \varphi(r) &\\
 \frac{\partial^2}{\partial x_k \partial y_k} &= -\frac{\partial}{\partial x_k} \frac{\alpha(x_j - x_{j_0})}{|r-r_0|^2}
 \end{aligned}$$

$$\begin{aligned} \sum_{j,k} x_j x_k \frac{\partial^2}{\partial x_k \partial x_j} \varphi(r) &= \sum_{j,k} x_j x_k \frac{\partial}{\partial x_k} \left(\frac{\alpha(x_j - x_0)}{|r - r_0|} \right) = \sum_{j,k} x_j x_k \left(\delta_{jk} \frac{-\alpha}{|r - r_0|^3} + \frac{3\alpha(x_j - x_{j0})(x_k - x_{k0})}{|r - r_0|^5} \right) \\ &= \sum_{j,k} x_j x_k \left(-\frac{\alpha \delta_{kj}}{r_0^3} + \frac{3\alpha x_{j0} x_{k0}}{r_0^5} \right) = \alpha \left(\frac{3(r - r_0)}{r_0^3} - \frac{r^2}{r_0^3} \right) \end{aligned}$$

2.3 Satz von Gauß

$$\oint_{S(V)} \vec{E} d\vec{f} = \int_V \vec{v} \cdot \vec{E} dV$$

$\vec{A} = (3xy, y, 0)$ über Halbkugel $r=1$ + Grundfläche

$$\vec{\nabla} \vec{A} = 3y + 1$$

$$\begin{aligned} \int_V 3y + 1 dV &= \int_0^{\pi/2} \int_0^\pi \int_0^r (3r \sin(\vartheta) \sin(\varphi) + 1) r^2 \sin(\vartheta) dr d\varphi d\vartheta = \int_0^{\pi/2} \int_0^1 2\pi r^2 \sin(\vartheta) dr d\vartheta \\ &= 2\pi \int_0^1 r^2 dr = \frac{2\pi}{3} \\ \int \vec{A} \cdot d\vec{r} &= \int_0^1 \vec{e}_r \cdot \vec{A} dF \\ \vec{e}_r \cdot \vec{A} &= \begin{pmatrix} \sin \vartheta \cos \varphi \\ \sin \vartheta \sin \varphi \\ \cos \vartheta \end{pmatrix} \begin{pmatrix} 3 \sin^2 \vartheta \cos \varphi \sin \varphi \\ \sin \vartheta \sin \varphi \\ 0 \end{pmatrix} \end{aligned}$$

3 Elektrodynamik Tutorium vom 12.11.2010

3.1 Beispiele

- $\int_{-\infty}^1 3xe^{-(x^2-1)} dx$ mit $t = x^2 - 1$, also $\frac{dt}{dx} = 2x$, $\frac{dt}{2x} = dx$
 $= \int_{\infty}^0 \frac{3}{2} e^{-t} dt = [-\frac{3}{2} e^{-t}]_{\infty}^0 = -\frac{3}{2}$
- $\int_0^5 (3x^2 - \frac{1}{x^2}) \delta(x-3) dx = 27 - \frac{1}{9}$
- $\vec{\nabla} \vec{r} = 3$
- $\vec{A} = (3xy, x^2, x^2 + y^2)$
 $\vec{\nabla} \vec{A} = 3y$
 $\vec{\nabla} \times \vec{A} = (2y, -2x, -x)$

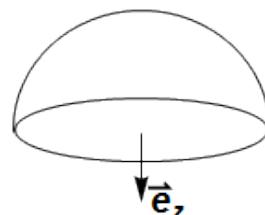
3.2 Fortsetzung: Halbkugel mit R=1

$$\vec{A} = (3xy, y, 0), \quad \int_V \vec{\nabla} \vec{A} dV = \frac{2}{3}\pi$$

$$\int_V \vec{\nabla} dV = \oint_{\partial V} \vec{A} d\vec{F}$$

$$\oint_{\partial V} \vec{A} d\vec{F} = \int_{\cap} \vec{e}_r \cdot \vec{A} dF - \int_0^{2\pi} \int_0^{\pi/2} \vec{e}_z \cdot \vec{A} dS = \int_0^{\pi/2} \int_0^{2\pi} \vec{e}_r \sin \vartheta \vec{A} R^2 d\vartheta d\varphi$$

$$\vec{e}_r \cdot \vec{A} = \begin{pmatrix} \sin \vartheta \cos \varphi \\ \sin \vartheta \sin \varphi \\ \cos \vartheta \end{pmatrix} \begin{pmatrix} 3 \sin^2 \vartheta \cos \varphi \sin \varphi \\ \sin \vartheta \sin \varphi \\ 0 \end{pmatrix} = 3 \sin^3 \vartheta \cos^2 \varphi \sin \varphi + \sin^2 \vartheta \sin^2 \varphi$$



$$\begin{aligned} \frac{d \cos \varphi}{d \varphi} &= -\sin \varphi \Leftrightarrow d \varphi = -\frac{d \cos \varphi}{\sin \varphi} \\ \Rightarrow \int_0^{\pi/2} \int_0^{2\pi} &\underbrace{(-3 \sin^4 \vartheta \cos^2 \varphi d \cos \varphi) d \vartheta}_{-\frac{1}{3} \cos^3 \varphi|_0^{2\pi}} + \int_0^{\pi/2} \int_0^{2\pi} \sin^3 \vartheta \sin^2 \varphi d \varphi d \vartheta = \pi \int_0^{\pi/2} \sin^3 \vartheta d \vartheta = \frac{2}{3} \pi \end{aligned}$$

3.3 Koordinatensysteme

$$\vec{e}_1, \vec{e}_2, \vec{e}_3$$

$$\vec{r} = \sum_{j=1}^3 x_j \vec{e}_j$$

$$d\vec{r} = \sum_{i=1}^3 dx_i \vec{e}_i = \sum_{i=1}^3 \frac{\partial r}{\partial x_i} dx_i$$

$$\vec{e}_{y_j} = \frac{\frac{\partial y_j}{\partial \vec{r}}}{|\frac{\partial \vec{r}}{\partial y_j}|}$$

$$e_{y_j} \cdot e_{y_i} = \delta_{ij}$$

Beispiel: $x = r \cos \varphi, y = r \sin \varphi$

$$e_r = \frac{\frac{\partial \vec{r}}{\partial r}}{|\frac{\partial \vec{r}}{\partial r}|}, \quad \frac{\partial \vec{r}}{\partial r} = \begin{pmatrix} \cos \varphi \\ \sin \varphi \end{pmatrix}$$

$$e_r = \begin{pmatrix} \cos \varphi \\ \sin \varphi \end{pmatrix}$$

$$e_\varphi = \frac{1}{r} \begin{pmatrix} -r \sin \varphi \\ r \cos \varphi \end{pmatrix} = \begin{pmatrix} -\sin \varphi \\ \cos \varphi \end{pmatrix}, \quad \frac{\partial \vec{r}}{\partial \varphi} = \begin{pmatrix} -r \sin \varphi \\ r \cos \varphi \end{pmatrix}$$

$$J = \frac{\partial(x,y)}{\partial(r,\varphi)} = \begin{vmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & -r \cos \varphi \end{vmatrix} = r \cos^2 \varphi + r \sin^2 \varphi = r$$

$$dV = dx_1 dx_2 = r dr d\varphi$$

3.4 Beispiel: parabolische Koordinaten

$$x = \frac{1}{2}(u^2 - v^2), \quad y = u \cdot v, \quad z' = z$$

$$\vec{e}_u = \frac{1}{\sqrt{u^2+v^2}} \hat{m} a t c u v 0$$

$$\vec{e}_v = \frac{1}{\sqrt{u^2+v^2}} \hat{m} a t c - v u 0$$

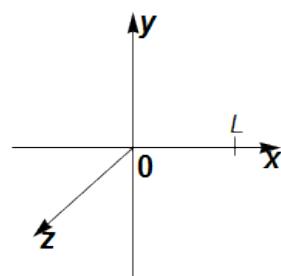
$$\vec{e}_z = \hat{m} a t c 0 0 1$$

$$J = \begin{vmatrix} u & -v & 0 \\ v & u & 0 \\ 0 & 0 & 1 \end{vmatrix} = u^2 + v^2 \Rightarrow dV = (u^2 + v^2) dudv$$

3.5 Ladungsverteilung Draht

$$\rho(\vec{r}) = \frac{Q}{L} \delta(x) \delta(z) \theta(L-x)$$

$$\theta(x - x_0) = \begin{cases} 0 & x - x_0 < 0 \\ 1 & x - x_0 > 0 \end{cases}$$



3.6 Ladungsverteilung Kugelschale

Radius R, Gesamt-Ladung Q.

$$\rho(\vec{r}) = \frac{Q}{4\pi R^2}$$

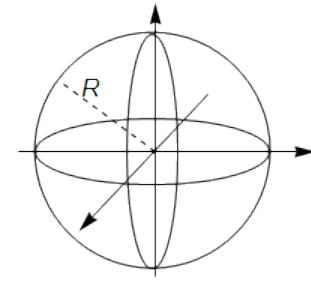
$$\int_V \vec{\nabla} \cdot \vec{E} d^3 r = \int_V \frac{\rho(\vec{r}')}{\epsilon_0} d^3 r' = \oint_{\partial V} \vec{E} \cdot \vec{n} dF$$

$$\int_V \frac{\rho(\vec{r}')}{\epsilon_0} d^3 r' = \frac{Q}{4\pi R^2 \epsilon_0} = \int_0^{pi} \int_0^{2\pi} \int_0^{R_a} \delta(r' - R) r'^2 \sin \vartheta dr' d\vartheta d\varphi = \frac{Q}{R^2 \epsilon_0} R^2 = \frac{Q}{\epsilon_0}$$

$$\vec{E}(\vec{r}) = E(r) \vec{e}_r$$

$$\oint_{\partial V} \vec{E} \cdot \vec{n} dF = \oint_{\partial V} E(r) \vec{e}_r \cdot \vec{e}_r dF = E(r) \int_0^\pi \int_0^{2\pi} R^2 \sin \vartheta d\vartheta d\varphi = 4\pi R^2 E(r)$$

$$E(r) = \begin{cases} \frac{Q}{4\pi \epsilon_0 R^2} & \text{für } r > R \\ 0 & \text{für } r \leq R \end{cases}$$



4 Elektrodynamik Tutorium vom 19.11.2010

4.1 Integrale

- $\int_{-\pi}^{\pi} \sin \theta \cos \theta d\theta : \sin \theta = x \Big| \frac{d \sin \theta}{d\theta} = \cos \theta \Rightarrow \dots = \int_0^0 x dx = 0$

- $\int_0^{\pi} \sin x e^x dx = \sin x e^x \Big|_0^{\pi} - \int_0^{\pi} \cos x e^x dx = -\cos x e^x \Big|_0^{\pi} + \int_0^{\pi} t \sin x e^x dx$
 $2 \int_0^{\pi} \sin x e^x dx = -\cos x e^x \Big|_0^{\pi} = e^{\pi} + 1$

4.2 Fortsetzung E-Feld Kugelschale

$$\rho(\vec{r}) = \frac{Q}{2\pi R} \delta(r' - R)$$

$$\int_V \vec{\nabla} \cdot \vec{E} d^3 r = \int_V \frac{\rho(\vec{r}')}{\epsilon_0} d^3 r' = \oint_{S(V)} \vec{E} \cdot \vec{n} dF = E(r) 4\pi r^2$$

$$\int_V \frac{\rho(\vec{r}')}{\epsilon_0} d^3 r' = \frac{Q}{\epsilon_0} \Rightarrow E(r) = \begin{cases} \frac{Q}{4\pi \epsilon_0 r^2} & \forall r > R \\ 0 & \forall r < R \end{cases}$$

4.3 Poisson-Gleichungen

$$\Delta \varphi(r) = -\frac{\rho(\vec{r})}{\epsilon_0}$$

Randbedingungen: $S(V)$, φ oder $\frac{\partial \varphi}{\partial n}$

$$\Rightarrow \varphi(r) = \underbrace{\frac{1}{4\pi \epsilon_0} \left(\int_V d^3 r' \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} \right)}_{\text{Ladung in Volumen}} + \underbrace{\frac{1}{4\pi} + \frac{1}{4\pi} \int_{S(V)} df' \left[\frac{1}{|\vec{r} - \vec{r}'|} \frac{\partial \varphi}{\partial n'} - \varphi(r') \frac{\partial}{\partial n'} \frac{1}{|\vec{r} - \vec{r}'|} \right]}_{\text{Ladung auf Oberfläche}}$$

Dirichlet: φ auf $S(V)$ (meistens)

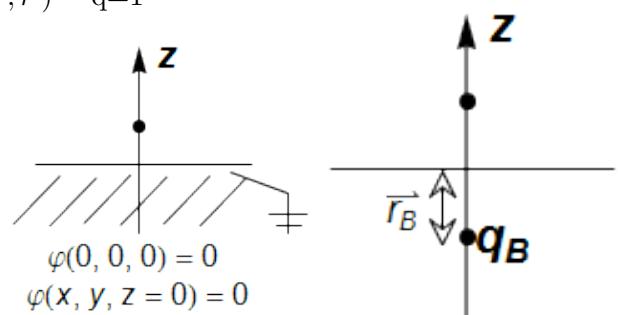
Neumann: $\frac{\partial \varphi}{\partial n}$ auf $S(V)$ (selten, Feld senkrecht zur Oberfläche ändernd... hier nicht)

Green'sche Fkt: $G(\vec{r}, \vec{r}') = \frac{1}{4\pi \epsilon_0} \frac{1}{|\vec{r} - \vec{r}'|} + f(\vec{r}, \vec{r}')$ q=1

Es muss gelten: $\Delta_r f(\vec{r}, \vec{r}') = 0$

$$D : \int_{S(V)} df' G_D(\vec{r}', \vec{r}) \frac{\partial \varphi}{\partial n'} = 0$$

$$G_D(\vec{r}, \vec{r}') = \frac{1}{4\pi \epsilon_0} \left(\frac{q}{|\vec{r}' - \vec{r}|} + \frac{q_B}{|\vec{r} - \vec{r}_B|} \right)$$



$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_V d^3 r' \rho(\vec{r}') \left(\frac{1}{|\vec{r}' - \vec{r}|} + \frac{1}{|\vec{r} - \vec{r}_B|} \right)$$

$$\text{Ansatz: } 4\pi\epsilon_0\varphi(r) = \frac{q}{|\vec{r}' - \vec{r}|} + \frac{q_B}{|\vec{r} - \vec{r}_B|} \stackrel{!}{=} 0$$

$$\Rightarrow q_B = -q \Rightarrow z_B = -z \Rightarrow \vec{r}_B = -\vec{r}$$

$$\Rightarrow 4\pi\epsilon_0\varphi(r) = \frac{q}{|\vec{r} - \vec{r}'|} - \frac{q}{|\vec{r} + \vec{r}'|}$$

$$E(r) = -\vec{\nabla} r \varphi(\vec{r}, \vec{r}')$$

$$\varphi(r) = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{|\vec{r} - \vec{r}'|} - \frac{1}{|\vec{r} + \vec{r}'|} \right) \Rightarrow \vec{r}'(0, 0, z)$$

$$\sigma = \epsilon_0 E(r, z=0), \bar{q} = \int \sigma dF$$

4.4 Fourier

$$\int_a^b f^*(x)f(x)dx = \|f(x)\|^2 = \int_a^b |f(x)|^2 dx < \infty$$

$$\{f_n(x)\}_{n=1,2,\dots}, \text{ orthogonal: } \int_a^b f_m^*(x)f_n(x)dx = \delta_{mn}$$

$$f(x) = \frac{1}{2}A_0 + \sum_{n=1}^{\infty} [A_n \cos \frac{2\pi nx}{a} + B_n \sin \frac{2\pi nx}{a}]$$

$$A_n = \frac{2}{a} \int_{-a/2}^{a/2} f(x) \cos \frac{2\pi nx}{a} dx, \quad B_n = \frac{2}{a} \int_{-a/2}^{a/2} f(x) \sin \frac{2\pi nx}{a} dx$$

5 Elektrodynamik Tutorium vom 26.11.2010

5.1 Kugelfunktion

$$\phi(r, \vartheta, \varphi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l (a_{lm} r^l + \frac{b_{lm}}{r^{l+1}}) Y_{lm}(\vartheta, \varphi)$$

Allg Lösung von $\Delta\phi = 0$

5.2 Integrale

- $\int_0^1 \frac{1}{x^3} \ln(x^2) dx$
 $\frac{1}{x^2} = a = x^{-2} \Leftrightarrow \frac{da}{dx} = -2x^{-3}, \ln(\frac{1}{a}) = -\ln(a)$
 $\Rightarrow \int_{\infty}^1 \frac{1}{2} \ln(a) da = \frac{1}{2} [-a + a \ln[a]]_1^{\infty} = \dots$

5.3 Hausaufgabenhinweise

gerade Funktion: $f(x) = f(-x) \Rightarrow \cos(x)$

ungerade Funktion: $-f(x) = f(-x) \Rightarrow \sin(x)$

$$\int_a^b f^*(x)f(x)dx = \|f(x)\|^2 = \int_a^b |f(x)|^2 dx = N$$

$$\int_a^b \frac{1}{\sqrt{N}} f^*(x) \frac{1}{\sqrt{N}} f(x) dx = \frac{N}{N} = 1$$

Fourier-Reihe:

$$f(x) = \frac{1}{2}A_0 + \sum_{n=1}^{\infty} [A_n \cos(\frac{2\pi nx}{a}) + B_n \sin(\frac{2\pi nx}{a})]$$

$$A_n = \frac{2}{a} \int_{-a/2}^{a/2} f(x) \cos(\frac{2\pi nx}{a}) dx$$

$$B_n = \frac{2}{a} \int_{-a/2}^{a/2} f(x) \sin\left(\frac{2\pi n x}{a}\right) dx$$

Fourier-Funktion:

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dk \tilde{f}(k) e^{ikx}$$

$$\tilde{f}(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dk f(x) e^{-ikx}$$

Beispiel: $f(x) = e^{-x^2/2}$

$$\tilde{f}(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dx e^{-x^2/2} e^{-ikx}$$

$$\text{Hinweis: } \int_{-\infty}^{\infty} dx e^{-x^2/a} = \pi$$

$$x^2 + 2ikx + (ik)^2 - (ik)^2 = (\underbrace{x+ik}_z)^2 + k^2$$

$$\Rightarrow \tilde{f}(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dx e^{\frac{-x^2-2ikx}{2}}$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dz e^{-z^2/2} e^{-k^2/2}$$

$$= \frac{1}{\sqrt{2\pi}} e^{-k^2/2} \int_{-\infty}^{\infty} e^{-z^2/2} dz = \frac{\sqrt{2\pi}}{\sqrt{2\pi}} e^{-k^2/2} = e^{-k^2/2}$$

5.4 geerdete Kugel

$$\text{Minimiert } \frac{q_1}{4\pi\epsilon_0} \frac{1}{|\vec{r}-\vec{r}_0|} + \frac{q_2}{4\pi\epsilon_0} \frac{1}{|\vec{r}+\vec{r}_0|} \text{ bei } f(\varphi(\vec{r}))_{r=R} = 0$$

$$= \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{|\vec{r}-\vec{r}_0|} + \frac{q_2}{|\vec{r}+\vec{r}_0|} + \frac{q_{B1}}{|\vec{r}-\vec{r}_{B1}|} + \frac{q_{B2}}{|\vec{r}-\vec{r}_{B2}|} \right)$$

$$\vec{r} = r\vec{e}_r, \quad \vec{r}_0 = r_0\vec{e}_{r_0}, \quad \vec{r}_{B1} = r_{B1}\vec{e}_{r_0}, \quad \vec{r}_{B2} = r_{B2}\vec{e}_{r_0} \Rightarrow \vec{r}_B \parallel \vec{r}_0$$

$$\varphi(r) = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{r} \frac{1}{|\vec{e}_r - \frac{r_0}{r} \vec{e}_{r_0}|} + \frac{q_2}{r} \frac{1}{|\vec{e}_r + \frac{r_0}{r} \vec{e}_{r_0}|} + \frac{q_{B1}}{r_{B1}} \frac{1}{|\frac{r}{r_{B1}} \vec{e}_r - \vec{e}_{r_0}|} + \frac{q_{B2}}{r_{B2}} \frac{1}{|\frac{r}{r_{B2}} \vec{e}_r + \vec{e}_{r_0}|} \right) =$$

$$= \varphi(r) = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{r} \frac{1}{(1 + \frac{r_0^2}{r^2} - 2 \frac{r_0}{r} \cos(\gamma))^{1/2}} + \frac{q_2}{r} \frac{1}{(1 + \frac{r_0^2}{r^2} + 2 \frac{r_0}{r} \cos(\gamma))^{1/2}} + \frac{q_{B1}}{r_{B1}} \frac{1}{(1 + \frac{r^2}{r_{B1}^2} - 2 \frac{r}{r_{B1}} \cos(\gamma))^{1/2}} + \frac{q_{B2}}{r_{B2}} \frac{1}{(1 + \frac{r^2}{r_{B2}^2} + 2 \frac{r}{r_{B2}} \cos(\gamma))^{1/2}} \right)$$

$$\Rightarrow -\frac{q_1}{R} = \frac{q_{B1}}{r_{B1}} \Rightarrow q_{B1} = -q_1 \frac{r_{B1}}{R}$$

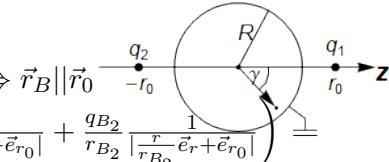
$$\Rightarrow -\frac{q_2}{R} = \frac{q_{B2}}{r_{B2}} \Rightarrow q_{B2} = -q_2 \frac{r_{B2}}{R}$$

$$1 + \frac{r_0^2}{R^2} - 2 \frac{r_0}{R} \cos(\gamma) = 1 + \frac{R^2}{r_{B1}^2} - 2 \frac{R}{r_{B1}} \cos(\gamma)$$

$$\Rightarrow \frac{r_0}{R} = \frac{R}{r_{B1}} \Rightarrow r_{B1} = \frac{R^2}{r_0}$$

$$\Rightarrow r_{B2} = \frac{R^2}{r_0}$$

$$\Rightarrow q_{B1} = -q_1 \frac{R}{r_0}, \quad q_{B2} = -q_2 \frac{R}{r_0} \Rightarrow \varphi(r) = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{|\vec{r}-\vec{r}_0|} + \frac{q_2}{|\vec{r}+\vec{r}_0|} - \frac{q_1}{|\vec{r}-\frac{R^2}{r_0^2}\vec{r}_0|} \frac{R}{r_0} - \frac{q_2}{|\vec{r}+\frac{R^2}{r_0^2}\vec{r}_0|} \frac{R}{r_0} \right)$$



6 Elektrodynamik Tutorium vom 3.12.2010

6.1 Anwendung Nabla in Kugelkoord

$$\Delta\phi = \vec{\nabla}^2\phi = 0,$$

$$\Delta = \frac{1}{r} \frac{\partial^2}{\partial r^2}(r) + \frac{1}{r^2 \sin(\vartheta)} \frac{\partial}{\partial \vartheta}(\sin(\vartheta) \frac{\partial}{\partial \vartheta}) + \frac{1}{r^2 \sin^2(\vartheta)} \frac{\partial^2}{\partial \varphi^2}$$

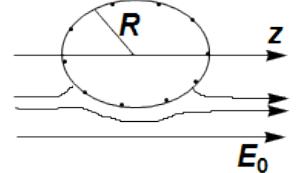
$$\Delta\phi = \vec{\nabla}^2\phi = \frac{1}{r} \frac{\partial^2}{\partial r^2}(r\phi) + \frac{1}{r^2 \sin(\vartheta)} \frac{\partial}{\partial \vartheta}(\sin(\vartheta) \frac{\partial\phi}{\partial \vartheta}) + \frac{1}{r^2 \sin^2(\vartheta)} \frac{\partial^2\phi}{\partial \varphi^2} = 0$$

$$\text{Ansatz: } \phi : (r, \vartheta, \varphi) = u(r)g(\vartheta)\chi(\varphi)$$

$$\begin{aligned}
0 &= \frac{g\lambda}{r} \frac{\partial^2 f}{\partial r^2} + \frac{fg}{r^3 \sin^2(\vartheta)} \frac{\partial^2 \chi}{\partial \varphi^2} + \frac{f\chi}{r^3 \sin \vartheta} \frac{\partial}{\partial \vartheta} (\sin(\vartheta) \frac{\partial g}{\partial \vartheta}) \quad | \cdot \frac{r^3 \sin^2(\vartheta)}{fg\chi} \\
0 &= \underbrace{\frac{r^2 \sin^2(\vartheta)}{f} \frac{\partial^2 f}{\partial r^2} + \frac{1}{\chi} \frac{\partial^2 \chi}{\partial \varphi^2}}_{-m^2=const} + \frac{\sin(\vartheta)}{g} \frac{\partial}{\partial \vartheta} (\sin(\vartheta) \frac{\partial g}{\partial \vartheta}) \\
\frac{1}{\chi} \frac{\partial^2 \chi}{\partial \varphi^2} + m^2 &= 0 \Leftrightarrow \frac{\partial^2 \chi}{\partial \varphi^2} + \chi m^2 = 0 \Rightarrow \chi(\varphi) = e^{\pm i m p} \frac{m^2}{\sin^2 \vartheta} = \underbrace{\frac{r^2}{f} \frac{\partial^2 f}{\partial r^2}}_{=:l(l+1)} + \frac{1}{g \sin(\vartheta)} \frac{\partial}{\partial \vartheta} (\sin(\vartheta) \frac{\partial g}{\partial \vartheta}) \\
r^2 \frac{1}{f} \frac{\partial^2 f}{\partial r^2} - l(l+1) &= 0 \\
\frac{\partial^2 f}{\partial r^2} - \frac{f}{r^2 l} (l+1) &= 0 \\
f(r) = r^\gamma &\Leftrightarrow \gamma(\gamma-1) = l(l+1) \Rightarrow \gamma = -l \vee \gamma = l+1 \\
f(r) &= A_l r^{l+1} + B_l r^{-l} \\
\Rightarrow 0 &= l(l+1) - \frac{m^2}{\sin^2(\vartheta)} + \frac{1}{g \sin(\vartheta)} \frac{\partial}{\partial \vartheta} (\sin(\vartheta) \frac{\partial g}{\partial \vartheta}) \\
&= (l(l+1) - \frac{m^2}{\sin^2(\vartheta)}) g + \frac{1}{\sin(\vartheta) \frac{\partial}{\partial \vartheta} (\sin(\vartheta) \frac{\partial g}{\partial \vartheta})} \\
\Rightarrow x &= \cos(\vartheta), \quad d\vartheta = -\frac{dx}{\sin(\vartheta)} \\
\Rightarrow 0 &= \frac{d}{dx} ((1-x^2) \frac{dg}{dx}) + [l(l+1) - \frac{m^2}{1-x^2}] g \\
g(x) &= \sum_{n=0}^{\infty} c_n x^n \\
\phi(r, \vartheta, \varphi, x = \cos(\vartheta)) &= (A_l r^l + B_l r^{-(l+1)}) \underbrace{g_l(x)}_{P_l} \\
\phi(r, \vartheta, \varphi) &= \sum_i P_i \\
\phi(r, \vartheta, \varphi) &= \sum_{i=0}^{\infty} \sum_{m=-l}^{+l} (A_{lm} r^l + B_{lm} r^{-(l+1)}) Y_{lm}(\vartheta, \varphi)
\end{aligned}$$

6.2 Beispiel: ungeladene Metallkugel

ungeladene Metallkugel in homogenen E-Feld \vec{E}_0



a) Symmetrie: Axialsymmetrie: keine φ -Abh.

$$\text{Allg. Potential: } \phi(r, \vartheta) = \sum_l (A_l r^l + B_l^{-l+1}) (2l+1) P_l(\cos(\vartheta))$$

b) Randbedingung:

$$\text{i) } r \rightarrow \infty \Rightarrow -\vec{\nabla} \phi^{(a)} = \vec{E}_0 \vec{e}_z \Leftrightarrow -\int E_0 dz = \phi^{(a)} = -E_0 z$$

$$\text{ii) } r < R, \quad E_{(i)} = 0 \Leftrightarrow -\vec{\nabla} \phi^{(i)} = \vec{E}_0 \Rightarrow \phi^{(i)} = \text{const} = 0$$

$$\text{iii) } \phi^{(i)}(R) = \phi^{(a)}(R)$$

$$\text{aus (ii) } \Rightarrow A_l^{(i)} = B_l^{(i)} = 0, \forall l$$

$$\text{iii) } \Rightarrow 0 = \phi^{(a)}(R) = \sum_i (A_l R^l + B_l R^{-(l+1)}) P_l(\cos(\vartheta)) (2l+1)$$

$$A_l R^l = \frac{-B_l}{R^{l+1}} \Leftrightarrow B_l = -A_l R^{2l+1}$$

$$\text{aus (i) } \Rightarrow \phi^{(a)}(r \rightarrow \infty) = -E_0 z = -E_0 r \cos(\vartheta) = -E_0 r P_1(\cos(\vartheta))$$

$$\phi^{(a)}(r) = \sum_i (A_l r^l - A_l R^{2l+1} r^{-(l+1)}) (2l+1) P_l(\cos(\vartheta))$$

$$\phi^{(a)}(r \rightarrow \infty) = 3A_1 r P_1(\cos(\vartheta)) = -E_0 r P_1(\cos(\vartheta))$$

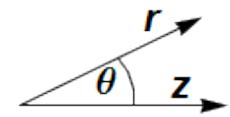
$$A_1 = -\frac{1}{3} E_0, \quad B_1 = E_0 \frac{R^3}{3}$$

$$\Rightarrow \phi(r, \vartheta) = \begin{cases} 0 & , r \leq R \\ (-E_0 r + \frac{E_0 R^3}{r^2} P_1(\cos(\vartheta))) & , r > R \end{cases}$$

6.3 Kugel mit Oberflächen-Ladung

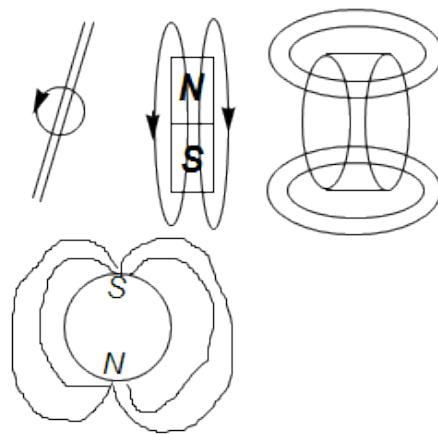
Kugel mit Oberflächenladung $\sigma(\theta) = \alpha(3\cos^2(\theta) - 1)$, $\alpha = \text{const}$
 Ansatz: $\phi = \sum_{l=0}^{\infty} (2l+1)(A_l r^l + B_l r^{-(l+1)} P_l(\cos(\vartheta)))$

- i) Regularität im Ursprung: $r \rightarrow 0 : \phi^i(r=0) \rightarrow \text{endlich}$
- ii) Endlichkeit: $r \rightarrow \infty : \phi^a(r \rightarrow \infty) \rightarrow \text{endlich}$
- iii) $\phi(R) = \phi^a(R)$
- iv) $\sigma(\theta) = -\varepsilon_0 (\frac{\partial \phi^a}{\partial r} - \frac{\partial \phi^i}{\partial r})|_{r=R}$



7 Elektrodynamik Tutorium vom 21.1.2011

7.1 Magnetfelder

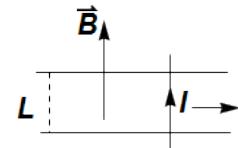


7.2 Induktionsgesetz

$$\begin{aligned} U &= \int \vec{\nabla} \times (\vec{\nabla} \times \vec{B}) d\vec{F} = - \int \Delta \vec{B} d\vec{F} \dots \\ &= -\frac{d}{dt} \int \vec{B} d\vec{F} \quad (\text{für } \frac{\partial \vec{B}}{\partial t} = 0) \\ \text{magnetischer Fluss: } \phi &= \int \vec{B} d\vec{F} \rightarrow U = \frac{d}{dt} \phi \end{aligned}$$

7.3 Beispiel: Leiterschleife durch Magnetfeld

$$\begin{aligned} \vec{F}_j &= \int \vec{j} \times \vec{B} dV \\ x(t=0) &= \dot{x}(t=0) = 0 \\ I &= \int_F \vec{j} dF \\ \vec{F}_L &= \int \vec{j} \times \vec{B} dV = B \int \vec{j} \times \vec{e}_z dV \\ &= B \int I \vec{e}_y \times \vec{e}_x dy \\ F &= m \dot{v} = IBL \Rightarrow \dot{v} = \frac{IBL}{m} \\ v &= \int \dot{v} dt = \dot{v} t + v_0 \\ \Rightarrow v &= \frac{IBL}{m} t \\ U_{ind} &= -\frac{d}{dt} \int \vec{B} d\vec{F} = -\frac{d}{dt} \int B \vec{e}_z \vec{e}_z dF \\ &= -B \frac{d}{dt} \int dF = -B \frac{d}{dt} L x(t) = -BLv = -\frac{IB^2 L^2}{m} t \end{aligned}$$



7.4 Maxwell-Gleichungen

stationär:

$$\begin{aligned}\vec{\nabla} \cdot \vec{D} &= \rho \\ \vec{\nabla} \times \vec{H} &= \vec{j} \\ \vec{\nabla} \cdot \vec{B} &= 0 \\ \vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t}\end{aligned}$$

allgemein:

inhomogen	homogen
$\vec{\nabla} \cdot \vec{D} = \rho$	$\vec{\nabla} \cdot \vec{B} = 0$
$\vec{\nabla} \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{j}$	$\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$
$\vec{B} = \mu \mu_0 \vec{H}$	$\vec{D} = \epsilon \epsilon_0 \vec{E}$
$\Rightarrow \begin{cases} \vec{E} = -\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t} \\ \vec{B} = \vec{\nabla} \times \vec{A} \end{cases}$	$\begin{cases} \vec{\nabla}^2 \vec{A} - \frac{1}{k^2} \frac{\partial^2 \vec{A}}{\partial t^2} = -\mu \mu_0 \vec{j} \\ \vec{\nabla}^2 \phi - \frac{1}{k^2} \frac{\partial^2 \phi}{\partial t^2} = -\frac{\rho}{\epsilon \epsilon_0} \end{cases}, \quad k = \frac{1}{\sqrt{\mu \mu_0 \epsilon \epsilon_0}} = c$
$\square = \vec{\nabla}^2 - \frac{1}{k^2} \frac{\partial^2}{\partial t^2}$ „Quabla“	

7.5 em-Wellen im Vakuum

$$\begin{aligned}\epsilon_0 \vec{E} &= \vec{D}, \quad \vec{B} = \mu_0 \vec{H}, \quad \rho = 0, \quad \vec{j} = 0 \\ \epsilon_0 \vec{\nabla} \cdot \vec{E} &= 0, \quad \vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0, \quad \vec{\nabla} \times \vec{B} = \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}, \quad \vec{\nabla} \cdot \vec{B} = 0 \\ \Rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{B}) &= \epsilon_0 \mu_0 \underbrace{\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{E})}_{-\frac{\partial \vec{B}}{\partial t}} \\ \Rightarrow -\Delta \vec{B} &= -\epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2} \vec{B} \\ \Delta \vec{B} - \underbrace{\epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2} \vec{B}}_{\frac{1}{c^2}} &= 0 \\ \vec{\nabla} \times (\vec{\nabla} \times \vec{E}) &= -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B}) \\ \Rightarrow \Delta \vec{E} &= -\underbrace{\epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2} \vec{E}}_{\frac{1}{c^2}}\end{aligned}$$

7.6 Lösung d. Wellengleichung

$$\begin{aligned}\vec{E} &= \vec{E}_0 e^{-i(\vec{k} \cdot \vec{r} - \omega t)} \\ \Delta \vec{E} &= \vec{E}_0 \Delta e^{-i(\vec{k} \cdot \vec{r} - \omega t)} = -\vec{k}^2 \vec{E} \\ \frac{\partial^2 \vec{E}}{\partial t^2} &= -\omega^2 \vec{E}, \quad \omega^2 = \vec{k}^2 c^2 \\ (-\vec{k}^2 + \frac{\omega^2}{c^2}) \vec{E} &= 0\end{aligned}$$

7.7 Eigenschaften von em-Wellen

$$\begin{aligned}\text{Wie stehen } \vec{k}, \vec{E}, \vec{B} \\ \vec{\nabla} \cdot \vec{E} = 0 = i \vec{k} \cdot \vec{E}, \quad \vec{k} \perp \vec{E} \quad \vec{\nabla} \cdot \vec{B} = 0 = i \vec{k} \cdot \vec{B}, \quad \vec{k} \perp \vec{B} \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \\ \Rightarrow i(\vec{k} \times \vec{E}) = i \omega \vec{B}, \quad \vec{E} \perp \vec{B}\end{aligned}$$

8 Elektrodynamik Tutorium vom 28.1.2011

8.1 Wellengleichung

homogene Wellengleichung: $\square\psi(\vec{r}, t) = \Delta - \frac{1}{u^2} \frac{\partial^2}{\partial t^2}$

$$\psi(\vec{r}, t) = f_-(\vec{k}\vec{r} - \omega t) + f_+(\vec{k}\vec{r} + \omega t), \quad u^2 k^2 = \omega^2$$

$$\vec{k} = k\vec{e}_z \Rightarrow \vec{k}\vec{r} = kz$$

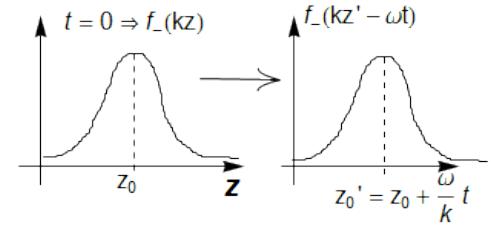
$$k = kz' - \omega t$$

$$z = z' - \frac{\omega}{k}$$

$$z'_0 = z_0 + \frac{\omega}{k}t$$

$$\frac{dz'}{dt} = \frac{\omega}{k} = u$$

Ansatz: $f_-(\vec{r}, t) = A e^{i(\vec{k}\vec{r} - \omega t)}$
 $f_+(\vec{r}, t) = B e^{i(\vec{k}\vec{r} + \omega t)}$
 $\Rightarrow \vec{E} = \vec{E}_0 e^{i(\vec{k}\vec{r} - \omega t)}, \quad \vec{B} = \vec{B}_0 e^{i(\vec{k}'\vec{r} - \omega' t)}$



Maxwell: $\vec{\nabla} \cdot \vec{E} = 0 \quad \vec{\nabla} \times \vec{E} = -\dot{\vec{B}}$
 $\vec{\nabla} \cdot \vec{B} = 0 \quad \vec{\nabla} \times \vec{B} = \frac{1}{u^2} \dot{\vec{E}}$
 $\Rightarrow \vec{k} \perp \vec{B}, \vec{E} \quad \vec{\nabla} \times \vec{E} = -\vec{B}$

$$i(\vec{k} \times \vec{E}_0) e^{i(\vec{k}\vec{r} - \omega t)} = i\omega' \vec{B}_0 e^{i(\vec{k}'\vec{r} - \omega' t)}$$

$$k = k', \quad \omega = \omega' \Rightarrow \vec{k} \times \vec{E}_0 = \omega \vec{B}_0, \quad \vec{k} \times \vec{B}_0 = \frac{\omega}{u^2} \vec{E}_0,$$

$$\vec{E}_0 = E_{0x} \vec{e}_x + E_{0y} \vec{e}_y$$

$$\vec{B}_0 = B_{0x} \vec{e}_x + B_{0y} \vec{e}_y$$

$$\vec{k} \times \vec{B}_0 = kB_{0x} \vec{e}_y - kB_{0y} \vec{e}_x$$

$$= -\frac{\omega}{u^2} e_{0x} \vec{e}_x - \frac{\omega}{u^2} e_{0y} \vec{e}_y$$

$$B_{0x} = -\frac{\omega}{u^2 k} E_{0y} = -\frac{\omega}{u} E_{0y}$$

$$B_{0y} = \frac{\omega}{u^2 k} E_{0x} = \frac{\omega}{u} E_{0x}$$

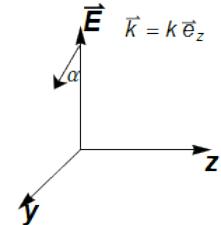
$$\Rightarrow \vec{E} = (E_{0x} \vec{e}_x + E_{0y} \vec{e}_y) e^{i(kz - \omega t)}$$

$$\Rightarrow \vec{B} = (-\frac{1}{u} E_{0x} \vec{e}_x + \frac{1}{u} E_{0y} \vec{e}_y) e^{i(kz - \omega t)}$$

$$E_{0x} = |E_{0x}| e^{i\varphi}, \quad E_{0y} = |E_{0y}| e^{i\varphi + \delta}$$

$$\vec{E} = (|E_{0x}| \vec{e}_x + |E_{0y}| \vec{e}_y e^{i\delta}) e^{i(kz - \omega t + \varphi)}$$

$$\Re(\vec{E}) = |E_{0x}| \vec{e}_x \cos(\xi) + |E_{0y}| \vec{e}_y e^{i\delta} (\cos(\delta) \cos(\xi) - \sin(\delta) \sin(\xi))$$



1. Fall: $\delta = 0, \pm \pi$
 $\Rightarrow \Re(\vec{E}) = (|E_{0x}| \vec{e}_x + |E_{0y}| \vec{e}_y) \cos(\xi)$
 $\tan(\alpha) = \frac{\pm |E_{0y}|}{|E_{0x}|}$
 (linear Polarisiert)
2. Fall $\delta = \pm \frac{\pi}{2}$
 $\Rightarrow \cos(\delta) = 0, \quad \sin(\delta) = \pm 1$
 $\Rightarrow \Re(\vec{E}) = (|E_{0x}| \vec{e}_x \cos(\xi) \mp |E_{0y}| \vec{e}_y \sin(\xi))$

8.2 Fourier-Transformation

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dk \tilde{F}(k) e^{ikx}$$

$$\tilde{F}(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dx f(k) e^{-ikx}$$

$$\begin{aligned}
\vec{k}\vec{x} &= k_x x + k_y y + k_z z \Rightarrow e^{i\vec{k}\vec{x}} = e^{ik_x x} + e^{ik_y y} + e^{ik_z z} \\
3\dim: & \frac{1}{\sqrt{2\pi}^3} \int dr^3 f(\vec{x}) e^{i\vec{k}\vec{x}} \\
\psi(\vec{r}, k) &= \frac{1}{(2\pi)^2} \int d^3k \int d\omega \tilde{\psi}(\vec{k}, \omega) e^{i(\vec{k}\vec{r} - \omega t)} \\
\delta(\vec{k} - \vec{k}') &= \frac{1}{(2\pi)^3} \int_{-\infty}^{\infty} d^3r e^{i\vec{x}(\vec{k} - \vec{k}')} \\
&\Rightarrow \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} d^3k \int_{-\infty}^{\infty} d\omega (-k^2 + \frac{\omega^2}{u^2}) \tilde{\psi}(\vec{k}, \omega) e^{i(\vec{k}\vec{r} - \omega t)} = 0 \\
\text{Multiplizieren mit } & e^{-i(\vec{k}'\vec{r} - \omega' t)} \int_{-\infty}^{\infty} d^3r \int_{-\infty}^{\infty} dk \\
e^{i\vec{k}\vec{r}} e^{-i\omega t} e^{-i\vec{k}'\vec{r}} &= e^{i(\vec{k} - \vec{k}')\vec{r}} e^{i(\omega' - \omega)t} \\
&\Rightarrow (-k'^2 + \frac{\omega^2}{u^2}) \tilde{\psi}(\vec{k}', \omega') = 0
\end{aligned}$$

9 Elektrodynamik Tutorium vom 11.2.2011

9.1 Aufgabe 1

Aufgabe:

$$\begin{aligned}
\tilde{f}(\omega) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt \\
f(t) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \tilde{f}(\omega) e^{i\omega x} d\omega \\
f(t) &= e^{-(\frac{t}{\Delta t})^2} \Rightarrow \tilde{f}(\omega) = ?
\end{aligned}$$

Lösung:

$$\begin{aligned}
\tilde{f}(\omega) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-(\frac{t}{\Delta t})^2} e^{-i\omega t} dt \\
&= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-((\frac{t}{\Delta t})^2 + i\omega t)} dt \\
&= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\frac{(t^2 + i\omega t \Delta t + (\frac{1}{2}i\omega \Delta t^2)^2) + (\frac{1}{2}i\omega \Delta t)^2}{\Delta t^2}} dt \\
&= \frac{1}{\sqrt{2\pi}} e^{-\frac{\frac{1}{4}\omega^2 \Delta t^4}{\Delta t^2}} \int_{-\infty}^{\infty} e^{-\frac{(t + \frac{1}{2}i\omega \Delta t^2)^2}{\Delta t^2}} dt \\
\text{Jetzt: Substitution } &z = t + \frac{1}{2}i\omega t^2, \quad \frac{\partial z}{\partial t} = 1 \\
&\Rightarrow \dots = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{4}\omega^2 \Delta t^2} \int_{-\infty}^{\infty} e^{-\frac{z^2}{\Delta t^2}} dz = \frac{1}{\sqrt{2}} \Delta t e^{-\frac{1}{4}\omega^2 \Delta t^2}
\end{aligned}$$

Bemerkung: Fouriertransformation von Gaußfkt. ist immer Gaußfkt.

9.2 Aufgabe 2

$$f(t) = e^{-\lambda t} \Rightarrow \tilde{f}(\omega) = ?$$

$$\begin{aligned}
\tilde{f}(\omega) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-\lambda t} e^{-i\omega t} dt = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{(-\lambda - i\omega)t} dt \\
&= \frac{1}{\sqrt{2\pi}} \left[\frac{1}{-\lambda - i\omega} e^{(-\lambda - i\omega)t} \right]_0^{\infty} = \frac{1}{\sqrt{2\pi}} \frac{1}{\lambda + i\omega}
\end{aligned}$$

9.3 Aufgabe 3: 3-Dim Fouriertransf.

Aufgabe:

$$\tilde{f}(\vec{k}) = \frac{1}{(2\pi)^{3/2}} \int d^3r f(\vec{r}) e^{i\vec{k}\vec{r}}$$

mit $e^{i\vec{k}\vec{r}} = e^{ik_x x + ik_y y + ik_z z}$ und $\boxed{f(r) = \frac{e^{-\mu r}}{r}} \quad (\mu > 0)$

Hinweis: $\int_0^\infty x^n e^{-\eta x} dx = n! \eta^{-n+1}$

Lösung:

$$\begin{aligned} \tilde{f}(\vec{k}) &= \frac{1}{(2\pi)^{3/2}} \int d^3r \frac{e^{-\mu r}}{r} e^{i\vec{k}\vec{r}} \\ &= \dots = \frac{1}{\sqrt{2\pi}} \int_0^\infty \int_0^\pi r e^{-\mu r} e^{ikr \cos(\theta)} d\cos(\theta) dr \\ &= \frac{1}{\sqrt{2\pi}} \int_0^\infty e^{-\mu r} [e^{-ikr} - e^{ikr}] dr \\ &= \frac{i}{k\sqrt{2\pi}} \left(\int_0^\infty e^{-r(\mu+ik)} dr - \int_0^\infty e^{-r(\mu-ik)} dr \right) \\ &= \frac{i}{k\sqrt{2\pi}} \left[\frac{1}{\mu+ik} - \frac{1}{\mu-ik} \right] = \frac{2}{\sqrt{2\pi}(\mu^2+k^2)} \end{aligned}$$

9.4 linearer, homogener, aufgeladener Isolator

$$\begin{array}{lll} \text{Maxwellgl:} & \vec{\nabla} \vec{E} = 0 & \vec{\nabla} \vec{B} = 0 \\ & \vec{\nabla} \times \vec{E} = -\dot{\vec{B}} & \vec{\nabla} \times \vec{B} = \frac{1}{u^2} \dot{\vec{E}} \end{array}$$

Aufgabe dazu:

$$\vec{E}(\vec{r}, t) = \frac{E_0}{5} (\vec{e}_x - 2\vec{e}_y) e^{i(\vec{k}\vec{r} - \omega t)} \quad \text{mit } \vec{k} = k\vec{e}_z \quad \vec{B}(\vec{r}, t) = ?$$

$$\Rightarrow \vec{\nabla} \times \vec{E} = -\dot{\vec{B}} = \begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} x \dots$$

$$\text{Ergebnis: } \vec{B}(\vec{r}, t) = \frac{E_0}{5} \frac{k}{\omega} e^{i(kz - \omega t)} (2\vec{e}_x + \vec{e}_y)$$

\Rightarrow Linear polarisiert, da $2\vec{e}_x + \vec{e}_y$ nicht zeitabhängig

Aufgabe 2:

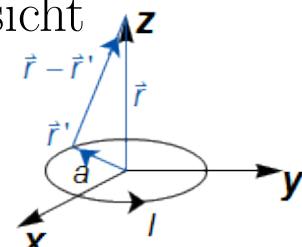
$$\begin{aligned} \vec{B}(\vec{r}, t) &= B_0 \cos(kz - \omega t) \vec{e}_x + B_0 \sin(kz - \omega t) \vec{e}_y \\ \vec{\nabla} \times \vec{B} &= \begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \times B_0 \begin{pmatrix} \cos(kz - \omega t) \\ \sin(kz - \omega t) \\ 0 \end{pmatrix} = -B_0 k \begin{pmatrix} \cos(kz - \omega t) \\ \sin(kz - \omega t) \\ 0 \end{pmatrix} \\ \Rightarrow B_0 \frac{k}{\omega} \frac{1}{u^2} \begin{pmatrix} -\sin(kz - \omega t) \\ \cos(kz - \omega t) \\ 0 \end{pmatrix} &= u B_0 \begin{pmatrix} -\sin(kz - \omega t) \\ \cos(kz - \omega t) \\ 0 \end{pmatrix} \end{aligned}$$

10 Elektrodynamik Tutorium vom 18.2.2011

Klausurvorbereitung: Aufgabenübersicht

10.1 Biot-Savart

$$\text{Biot-Savart: } B(\vec{r}) = \frac{\mu_0 I}{4\pi} \int_c d\vec{r}' \times \frac{(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$



$$\begin{aligned}
\vec{r}' &= \vec{r}'(\varphi) = \begin{pmatrix} a \cos(\varphi) \\ a \sin(\varphi) \\ 0 \end{pmatrix}, \quad \varphi \in [0, 2\pi) \\
\vec{r}_0 ? \vec{r} - \vec{r}' &= \begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix} - \begin{pmatrix} a \cos(\varphi) \\ a \sin(\varphi) \\ 0 \end{pmatrix} = \begin{pmatrix} -a \cos(\varphi) \\ -a \sin(\varphi) \\ z \end{pmatrix} \\
|\vec{r}_0^3| &= (a^2 + z^2)^{3/2} \\
d\vec{r}' &= \frac{d\vec{r}}{d\varphi} d\varphi = \begin{pmatrix} -a \sin(\varphi) \\ a \cos(\varphi) \\ 0 \end{pmatrix} \\
d\vec{r} \times \vec{r}_0 &= \begin{pmatrix} az \cos(\varphi) \\ az \sin(\varphi) \\ a^2 \end{pmatrix} d\varphi \\
\Rightarrow \vec{B}(\vec{r}) &= \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{1}{r_0^3} \begin{pmatrix} az \cos(\varphi) \\ az \sin(\varphi) \\ a^2 \end{pmatrix} d\varphi \\
&= \frac{\mu_0 I}{2} \frac{a^2}{(a^2 + z^2)^{3/2}}
\end{aligned}$$

10.2 Magnetfeld

Gefragt: B im ganzen Raum

$$\oint_c \vec{B} d\vec{r} = \mu_0 \int_{S(c)} \vec{j} d\vec{f}$$

$$\vec{B}(\vec{r}) = B(\vec{r}) \vec{e}_\varphi$$

$$\text{L.S.: } \oint_c \vec{B} d\vec{r} = \int_0^{2\pi} r B(\vec{r}) d\varphi = 2\pi r B(\vec{r})$$

R.S.:

1. Fall $r \leq R_1$:

$$B(\vec{r}) = 0, \text{ da } j \text{ für } r \leq R_1 0 \text{ ist}$$

2. Fall $R_1 \leq r \leq R_2$:

$$\begin{aligned}
&\mu_0 \int_0^r \int_0^{2\pi} j r dr d\varphi \\
&= \mu_0 \left[\int_0^{R_1} \int_0^{2\pi} j_i r dr d\varphi + \int_{R_1}^r \int_0^{2\pi} r j dr d\varphi \right] \\
&= \mu_0 \pi j (r^2 - R_1^2)
\end{aligned}$$

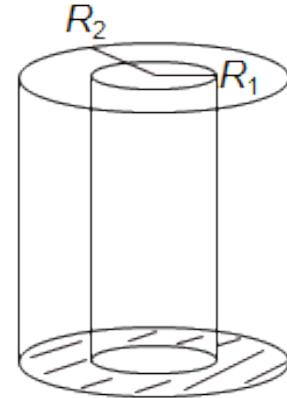
$$I = \pi j (R_2^2 - R_1^2) \Rightarrow j = \frac{I}{\pi(R_2^2 - R_1^2)}$$

$$\Rightarrow \dots = \mu_0 I \frac{(r^2 - R_1^2)}{(R_2^2 - R_1^2)}$$

3. Fall $R_2 \leq r$:

$$\begin{aligned}
&\mu_0 \int_0^r \int_0^{2\pi} \dots = \mu_0 \left[0 + \int_{R_1}^{R_2} \int_0^{2\pi} j r dr d\varphi + 0 \right] \\
&= \pi \mu_0 j (R_2^2 - R_1^2) = \mu_0 I
\end{aligned}$$

$$B(\vec{r}) = \frac{\mu_0 I}{2\pi} \begin{cases} 0 & r \leq R_1 \\ \frac{r}{R_2^2 - R_1^2} & R_1 \leq r \leq R_2 \\ \frac{1}{r} & R_2 \leq r \end{cases}$$



10.3 Schwingkreis

$$U_R = IR$$

$$U_C = \frac{U}{C}$$

$$U_L = -LI$$

$$I = \dot{Q}$$

$$U_R = U_e - U_C + U_L \Leftrightarrow IR = U_e - \frac{Q}{C} - LI$$

10.4 Wellenpakete

$$H_{\pm} = \int_{-\infty}^{\infty} b(k) e^{i(kz \pm wt)} dt$$

10.5 Energie-/Energiestromdichte

$$\bar{A}(\vec{r}) = \frac{1}{t} \int_t^{t+\tau} dt' A(\vec{r}, t')$$

$$\omega(\vec{r}, t) = \frac{1}{2} (\vec{H}(\vec{r}, t) \vec{B}(\vec{r}, t) + \vec{E}(\vec{r}, t) \vec{D}(\vec{r}, t))$$

$$\vec{s}(\vec{r}, t) = (\vec{E}(\vec{r}, t) \times \vec{H}(\vec{r}, t))$$

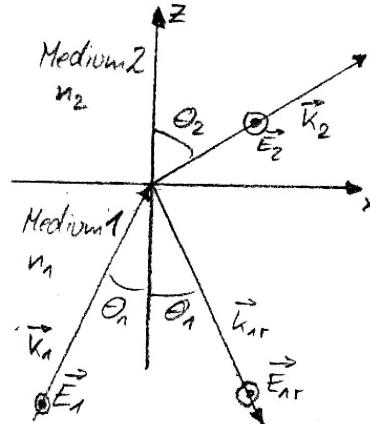
10.6 Brechung/Reflexion

$$\vartheta_1 = \vartheta_{1r}$$

$$\frac{\sin(\vartheta_1)}{\sin(\vartheta_2)} = \frac{n_2}{n_1}$$

$$R = |\frac{n_1 - 1}{n_1 + 1}|^2 \text{ und } R + T = 1$$

10.7 Blatt 13, NR.3



$$1) \vec{\nabla} \times [\vec{E}_2 - (\vec{E}_1 + \vec{E}_{1r})] = 0$$

$$2) \vec{\nabla} \cdot [\varepsilon_{r2} \vec{E}_2 - \varepsilon_{r1} (\vec{E}_1 + \vec{E}_{1r})] = 0$$

$$3) \vec{\nabla} \times [\frac{1}{\mu_{r2}} (\vec{k}_2 \times \vec{E}_2) - \frac{1}{\mu_{r1}} (\vec{k}_1 \times \vec{E}_1 + \vec{k}_{1r} \times \vec{E}_{1r})] = 0$$

$$4) \vec{\nabla} \cdot [(\vec{k}_2 \times \vec{E}_2) - (\vec{k}_1 \times \vec{E}_1 + \vec{k}_{1r} \times \vec{E}_{1r})] = 0$$

$$\vec{k} = \begin{pmatrix} k_x \\ 0 \\ k_z \end{pmatrix} = \begin{pmatrix} k \sin(\theta) \\ 0 \\ k \cos(\theta) \end{pmatrix}$$

$$\vec{E} = \begin{pmatrix} 0 \\ E_y \\ 0 \end{pmatrix}$$

- $\vec{k} \cdot \vec{E} = 0$

- $\vec{E} \cdot \vec{e}_z = 0$

- $\vec{I} \times \vec{E} = (-E_y k \cos(\theta), 0, E_y k \sin(\theta))$

- $(\vec{k} \times \vec{E}) \cdot \vec{e}_z = E_y k \sin(\theta)$

- $\vec{E} \times \vec{e}_z = (0, 0, 0)$

- $(\vec{k} \times \vec{E}) \times \vec{e}_z = (0, E_y k \cos(\theta), 0)$

(3) $-E_{02} k_{z2} + E_{01} k_{z1} + E_{1r} k_{z1r} = 0$

$$\begin{aligned}
 \textcircled{1} \quad & -E_{02} + E_{01} + E_{01r} = 0 \Rightarrow E_{02} = E_{01} + E_{01r} \\
 \Rightarrow & -E_{01}k_{z2} - E_{01r}k_{2z} + E_{01}k_{z1} - E_{01r}k_{z1} = 0 \\
 E_{01}(k_{z1} - k_{z2}) &= E_{01r}(k_{z2} + k_{z1}) \\
 \frac{E_{01r}}{E_{01}} &= \frac{k_{z1} - k_{z2}}{k_{z2} + k_{z1}} = \frac{k_1 \cos(\theta_1) - k_2 \cos(\theta_2)}{k_2 \cos(\theta_2) + k_1 \cos(\theta_1)} \\
 k_2 &= k_1 \frac{n_2}{n_1} \\
 \Rightarrow \frac{E_{01r}}{E_{01}} &= \frac{k_1 \cos(\theta_1) - k_1 \frac{n_2}{n_1} \cos(\theta_2)}{k_1 \frac{n_2}{n_1} \cos(\theta_2) + k_1 \cos(\theta_1)} \\
 &= \frac{n_1 \cos(\theta_1) - n_2 \cos(\theta_2)}{n_2 \cos(\theta_2) + n_1 \cos(\theta_1)}
 \end{aligned}$$