

P19

(a) The apparent velocity at any time t is

$$dr/dt = 2ti - 6j + 12t^2k$$

At time $t = 1$ this is $2i - 6j + 12k$.

The true velocity at any time t is

$$dr/dt + \omega \times r = (2ti - 6j + 12t^2k) + [2ti - t^2j + (2t + 4)k] \times [(t^2 + 1)i - 6tj + 4t^3k]$$

At time $t = 1$ this is

$$2i - 6j + 12k + \begin{vmatrix} i & j & k \\ 2 & -1 & 6 \\ 2 & -6 & 4 \end{vmatrix} = 34i - 2j + 2k$$

(b)

The apparent acceleration at any time t is

$$\frac{d^2r}{dt^2} = \frac{d}{dt} \left(\frac{dr}{dt} \right) = \frac{d}{dt} (2ti - 6j + 12t^2k) = 2i + 24tk$$

At time $t = 1$ this is $2i + 24k$.

The true acceleration at any time t is

$$\frac{d^2r}{dt^2} + 2\omega \times \frac{dr}{dt} + \frac{d\omega}{dt} \times r + \omega \times (\omega \times r)$$

At time $t = 1$ this equals

$$\begin{aligned} & 2i + 24k + (4i - 2j + 12k) \times (2i - 6j + 12k) \\ & + (2i - 2j + 2k) \times (2i - 6j + 4k) \\ & + (2i - j + 6k) \times \{(2i - j + 6k) \times (2i - 6j + 4k)\} \\ & = 2i + 24k + (48i - 24j - 20k) + (4i - 4j - 8k) + (-14i + 212j + 40k) \\ & = 40i + 184j + 36k \end{aligned}$$

(c)

From Problem (a) we have,

$$\begin{aligned} \text{Coriolis acceleration} &= 2\omega \times dr/dt = (4i - 2j + 12k) \times (2i - 6j + 12k) \\ &= 48i - 24j - 20k \end{aligned}$$

From Problem (a) we have,

$$\begin{aligned} \text{Centripetal acceleration} &= \omega \times (\omega \times r) = (2i - j + 6k) \times (32i + 4j - 10k) \\ &= -14i + 212j + 40k \end{aligned}$$

$$\begin{aligned} \text{Magnitude of Coriolis acceleration} &= \sqrt{(48)^2 + (-24)^2 + (-20)^2} = 4\sqrt{205} \\ \text{Magnitude of centripetal acceleration} &= \sqrt{(-14)^2 + (212)^2 + (40)^2} = 2\sqrt{11,685} \end{aligned}$$

P20

Choose the xyz coordinate system of Fig. 1. Suppose that the origin O is the equilibrium position of the bob B , A is the point of suspension and the length of string AB is l . If the tension in the string is \mathbf{T} , then we have

$$\begin{aligned}\mathbf{T} &= (\mathbf{T} \cdot \mathbf{i})\mathbf{i} + (\mathbf{T} \cdot \mathbf{j})\mathbf{j} + (\mathbf{T} \cdot \mathbf{k})\mathbf{k} \\ &= T \cos \alpha \mathbf{i} + T \cos \beta \mathbf{j} + T \cos \gamma \mathbf{k} \\ &= -T \left(\frac{x}{l} \right) \mathbf{i} - T \left(\frac{y}{l} \right) \mathbf{j} + T \left(\frac{l-z}{l} \right) \mathbf{k} \quad (1)\end{aligned}$$

Since the net force acting on B is $\mathbf{T} + m\mathbf{g}$, the equation of motion of B is given by [see Problem 6.14]

$$m \frac{d^2 \mathbf{r}}{dt^2} = \mathbf{T} + m\mathbf{g} - 2m(\boldsymbol{\omega} \times \mathbf{v}) - m\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) \quad (2)$$

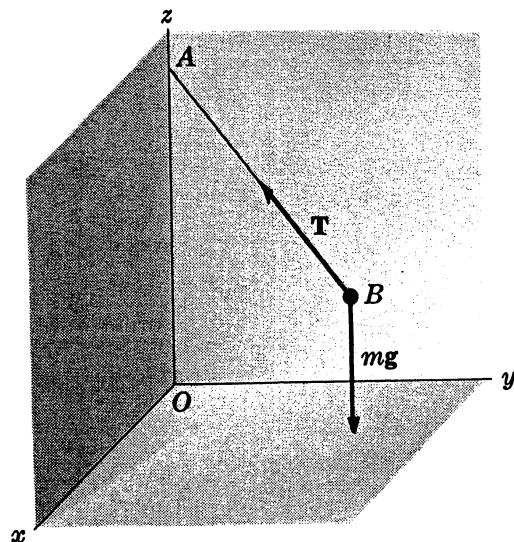


Fig 1

If we neglect the last term in (2), put $\mathbf{g} = -g\mathbf{k}$ and use (1), then (2) can be written in component form as

$$m \ddot{x} = -T(x/l) + 2m\omega \dot{y} \cos \lambda \quad (3)$$

$$m \ddot{y} = -T(y/l) - 2m\omega(\dot{x} \cos \lambda + \dot{z} \sin \lambda) \quad (4)$$

$$m \ddot{z} = T(l-z)/l - mg + 2m\omega \dot{y} \sin \lambda \quad (5)$$