

H18

- a) $\frac{d\vec{A}}{dt}|_F = \frac{d\vec{A}}{dt}|_M + \vec{\omega} \times \vec{A}$
 $\Rightarrow \frac{d\vec{\omega}}{dt}|_F = \frac{d\vec{\omega}}{dt}|_M + \vec{\omega} \times \vec{\omega} = \frac{d\vec{\omega}}{dt}|_M$
- b) $\frac{d\vec{x}}{dt}|_F = \frac{d\vec{x}}{dt}|_M + \vec{\omega} \times \vec{x}$
- c) $\frac{d\vec{v}}{dt}|_F = \frac{d\vec{v}}{dt}|_M + \vec{\omega} \times \vec{v}$

H19

- a) $\ddot{\vec{x}}(t) = -g\vec{e}_z$
 $\Rightarrow \dot{\vec{x}}(t) = -gt\vec{e}_z + \vec{v}_0$
 Sei $\lambda = \arctan(\frac{v_y}{v_x})$, $v_{xy} = \sqrt{v_x^2 + v_y^2} \Rightarrow \dot{\vec{x}}(t) = -gt\vec{e}_z + \begin{pmatrix} v_{xy} \cos(\lambda) \\ v_{xy} \sin(\lambda) \\ v_z \end{pmatrix}$
 $\Rightarrow \vec{x}(t) = -\frac{1}{2}gt^2\vec{e}_z + \begin{pmatrix} v_{xy} \cos(\lambda) \\ v_{xy} \sin(\lambda) \\ v_z \end{pmatrix} t$
 $\Rightarrow \vec{x}'(t) = -\frac{1}{2}gt^2\vec{e}_z + \begin{pmatrix} v_{xy} \cos(\lambda - \omega t) \\ v_{xy} \sin(\lambda - \omega t) \\ v_z \end{pmatrix} t$
- b) $\ddot{\vec{x}}' = -g\vec{e}_z + 2\dot{\vec{x}}' \times \vec{\omega} + \vec{\omega} \times (\vec{\omega} \times \dot{\vec{x}}(t)) = -g\vec{e}_z + 2 \begin{pmatrix} \omega v_{xy} \sin(\lambda - \omega t) \\ -\omega v_{xy} \cos(\lambda - \omega t) \\ 0 \end{pmatrix} + \begin{pmatrix} -t\omega^2 v_{xy} \cos(\lambda - t\omega) \\ -t\omega^2 v_{xy} \sin(\lambda - t\omega) \\ 0 \end{pmatrix}$
 $\dot{\vec{x}}'(t) = -gt\vec{e}_z + 2 \begin{pmatrix} v_{xy} \cos(\lambda - \omega t) \\ v_{xy} \sin(\lambda - \omega t) \\ 0 \end{pmatrix} + \begin{pmatrix} t\omega v_{xy} \sin(\lambda - \omega t) \\ -t\omega v_{xy} \cos(\lambda - \omega t) \\ 0 \end{pmatrix} + \begin{pmatrix} -v_{xy} \cos(\lambda - \omega t) \\ -v_{xy} \sin(\lambda - \omega t) \\ 0 \end{pmatrix} + v'_0$
 $= -gt\vec{e}_z + \begin{pmatrix} v_{xy} \cos(\lambda - \omega t) \\ v_{xy} \sin(\lambda - \omega t) \\ 0 \end{pmatrix} + \begin{pmatrix} t\omega v_{xy} \sin(\lambda - \omega t) \\ -t\omega v_{xy} \cos(\lambda - \omega t) \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ v_z \end{pmatrix}$
 $\Rightarrow \vec{x}'(t) = -\frac{1}{2}gt^2\vec{e}_z + \frac{1}{\omega} \begin{pmatrix} -v_{xy} \sin(\lambda - t\omega) \\ v_{xy} \cos(\lambda - t\omega) \\ 0 \end{pmatrix} + \frac{1}{\omega} \begin{pmatrix} v_{xy} \sin(\lambda - \omega t) \\ -v_{xy} \cos(\lambda - \omega t) \\ 0 \end{pmatrix}$
 $+ \begin{pmatrix} t v_{xy} \cos(\lambda - \omega t) \\ t v_{xy} \sin(\lambda - \omega t) \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ v_z t \end{pmatrix}$
 $= -\frac{1}{2}gt^2\vec{e}_z + \begin{pmatrix} v_{xy} \cos(\lambda - \omega t) \\ v_{xy} \sin(\lambda - \omega t) \\ v_z \end{pmatrix} t$