

Vorbereitung 1 zu E-Dynamik

Vorbereitung 1 zu E-Dynamik

✓
$$\begin{vmatrix} \delta_{i1} & \delta_{i2} & \delta_{i3} \\ \delta_{j1} & \delta_{j2} & \delta_{j3} \\ \delta_{k1} & \delta_{k2} & \delta_{k3} \end{vmatrix} = \overbrace{\delta_{i1}\delta_{j2}\delta_{k3}}^{1,2,3 \rightarrow 1 \text{ sonst } 0} + \overbrace{\delta_{i2}\delta_{j3}\delta_{k1}}^{2,3,1 \rightarrow 1 \text{ sonst } 0} + \overbrace{\delta_{i3}\delta_{j1}\delta_{k2}}^{3,1,2 \rightarrow 1 \text{ sonst } 0} - \overbrace{\delta_{i1}\delta_{j3}\delta_{k2}}^{1,3,2 \rightarrow -1 \text{ sonst } 0} - \overbrace{\delta_{i2}\delta_{j1}\delta_{k3}}^{2,1,3 \rightarrow -1 \text{ sonst } 0} - \overbrace{\delta_{i3}\delta_{j2}\delta_{k1}}^{3,2,1 \rightarrow -1 \text{ sonst } 0}$$

\Rightarrow gerade Anz. Perm. = 1

\Rightarrow ungerade Anz. Perm. = -1

\Rightarrow sonst 0 $\Rightarrow \dots = \epsilon_{ijk}$

$$\epsilon_{ijk} \epsilon_{lmn} = \begin{vmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{vmatrix} = |(\dots) \cdot (\dots)|$$

$$= \begin{vmatrix} \delta_{i1}\delta_{1k} + \delta_{i2}\delta_{2k} + \delta_{i3}\delta_{3k} & \delta_{i1}\delta_{1m} + \delta_{i2}\delta_{2m} + \delta_{i3}\delta_{3m} & \delta_{i1}\delta_{1k} + \delta_{i2}\delta_{2k} + \delta_{i3}\delta_{3k} \\ \delta_{j1}\delta_{1l} + \delta_{j2}\delta_{2l} + \delta_{j3}\delta_{3l} & \delta_{j1}\delta_{1m} + \delta_{j2}\delta_{2m} + \delta_{j3}\delta_{3m} & \delta_{j1}\delta_{1k} + \delta_{j2}\delta_{2k} + \delta_{j3}\delta_{3k} \\ \delta_{k1}\delta_{1l} + \delta_{k2}\delta_{2l} + \delta_{k3}\delta_{3l} & \delta_{k1}\delta_{1m} + \delta_{k2}\delta_{2m} + \delta_{k3}\delta_{3m} & \delta_{k1}\delta_{1k} + \delta_{k2}\delta_{2k} + \delta_{k3}\delta_{3k} \end{vmatrix}$$

$$= \cancel{\delta_{kl}} \begin{vmatrix} \delta_{im} & \delta_{ik} \\ \delta_{jm} & \delta_{jk} \end{vmatrix} - \delta_{km} \begin{vmatrix} \delta_{il} & \delta_{ik} \\ \delta_{jl} & \delta_{jk} \end{vmatrix} + 3 \begin{vmatrix} \delta_{il} & \delta_{im} \\ \delta_{jl} & \delta_{jm} \end{vmatrix}$$

$$= \begin{vmatrix} \delta_{im} & \delta_{ik} & \delta_{il} \\ \delta_{jm} & \delta_{jk} & \delta_{jl} \end{vmatrix} - \begin{vmatrix} \delta_{il} & \delta_{ik} & \delta_{km} \\ \delta_{jl} & \delta_{jk} & \delta_{km} \end{vmatrix} + 3 \dots = \begin{vmatrix} \delta_{im} & \delta_{il} \\ \delta_{jm} & \delta_{jl} \end{vmatrix} - \begin{vmatrix} \delta_{il} & \delta_{im} \\ \delta_{jl} & \delta_{jm} \end{vmatrix} + 3 \dots$$

$$= (3-2) \begin{vmatrix} \sigma_{il} & \sigma_{im} \\ \sigma_{jl} & \sigma_{jm} \end{vmatrix} = \sigma_{il}\sigma_{jm} - \sigma_{im}\sigma_{jl}$$

$$\epsilon_{ijk} \epsilon_{cij} = \cancel{\delta_{il} \delta_{jj} - \delta_{ij} \delta_{il}} = \cancel{\delta_{il} - \delta_{il}} \quad \cancel{\sum_k \left(\sum_{j,l} (\epsilon_{ijk} \epsilon_{cij}) \right) = \sum_k (\delta_{jj} \delta_{kk} - \delta_{jk} \delta_{kj})}$$

$$\sum_k \left(\sum_j (\epsilon_{jki} \epsilon_{jkl}) \right) = \sum_k (\delta_{kk} \delta_{il} - \delta_{kl} \delta_{il}) = 3 \delta_{il} - \delta_{il} = 2 \delta_{il}$$

$$\varepsilon_{ijk}\varepsilon_{ijk} = \sum_i \left(\sum_j \left(\sum_k (\varepsilon_{ijk}\varepsilon_{ijk}) \right) \right) = \sum_i \left(\sum_j \left(\sum_k (\delta_{ij}\delta_{ik} - \delta_{ik}\delta_{ji}) \right) \right) = \sum_i (3 - \delta_{ii}) = 9 - 3 = 6$$

$$2/ \vec{a} \times \vec{b} = \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix}; \sum_{i,j,k=1}^3 \epsilon_{ijk} a_j b_k \vec{e}_i = \begin{pmatrix} \epsilon_{123} a_2 b_3 + \epsilon_{132} a_3 b_2 \\ \epsilon_{231} a_3 b_1 + \epsilon_{213} a_1 b_3 \\ \epsilon_{312} a_1 b_2 + \epsilon_{321} a_2 b_1 \end{pmatrix} = \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix} \Rightarrow \vec{a} \times \vec{b} = \epsilon_{ijk} a_j b_k \vec{e}_i$$

$$\vec{\nabla} \times \vec{v} = \begin{pmatrix} \partial_2 v_3 - \partial_3 v_2 \\ \partial_3 v_1 - \partial_1 v_3 \\ \partial_1 v_2 - \partial_2 v_1 \end{pmatrix} \quad \sum_{i,j,k=1}^3 \epsilon_{ijk} \partial_j v_k \vec{e}_i = \dots = \begin{pmatrix} \partial_2 v_3 - \partial_3 v_2 \\ \partial_3 v_1 - \partial_1 v_3 \\ \partial_1 v_2 - \partial_2 v_1 \end{pmatrix} \Rightarrow \checkmark$$

$$3/ a) \vec{\nabla}(\vec{a} \cdot \vec{b}) = \vec{\nabla}(a_1 b_1 + a_2 b_2 + a_3 b_3) = \begin{pmatrix} \partial_1 a_1 b_1 \\ \partial_2 a_1 b_1 \\ \partial_3 a_1 b_1 \end{pmatrix} = \begin{pmatrix} b_1 \partial_1 a_1 + a_1 \partial_1 b_1 \\ b_1 \partial_2 a_1 + a_1 \partial_2 b_1 \\ b_1 \partial_3 a_1 + a_1 \partial_3 b_1 \end{pmatrix}$$

$$= \begin{pmatrix} a_1 \partial_1 b_1 \\ a_1 \partial_2 b_1 \\ a_1 \partial_3 b_1 \end{pmatrix} + \begin{pmatrix} b_1 \partial_1 a_1 \\ b_1 \partial_2 a_1 \\ b_1 \partial_3 a_1 \end{pmatrix} + \begin{pmatrix} b_2 \partial_1 a_2 + b_3 \partial_1 a_3 - b_2 \partial_2 a_1 - b_3 \partial_3 a_1 \\ -b_1 \partial_1 a_2 + b_1 \partial_2 a_1 + b_3 \partial_2 a_3 - b_3 \partial_3 a_2 \\ -b_1 \partial_1 a_3 - b_2 \partial_2 a_3 + b_1 \partial_3 a_1 - b_2 \partial_3 a_2 \end{pmatrix} + \begin{pmatrix} a_2 \partial_1 b_2 + a_3 \partial_1 b_3 - a_2 \partial_2 b_1 - a_3 \partial_3 b_1 \\ -a_1 \partial_1 b_2 + a_1 \partial_2 b_3 + a_3 \partial_2 b_3 - a_3 \partial_3 b_2 \\ -a_1 \partial_1 b_3 - a_2 \partial_2 b_3 + a_1 \partial_3 b_1 - a_2 \partial_3 b_2 \end{pmatrix}$$

$$= \begin{pmatrix} a_1 \partial_1 b_1 + b_1 \partial_1 a_1 + a_2 \partial_2 b_2 + b_2 \partial_2 a_2 + a_3 \partial_3 b_3 + b_3 \partial_3 a_3 + b_2 \partial_1 a_2 + b_3 \partial_1 a_3 - b_2 \partial_2 a_1 - b_3 \partial_3 a_1 + a_2 \partial_1 b_2 \\ + a_3 \partial_1 b_3 - a_2 \partial_2 b_1 - a_3 \partial_3 b_1 \\ a_2 \partial_1 b_2 + b_2 \partial_1 a_1 + a_2 \partial_2 b_2 + b_2 \partial_2 a_2 + a_2 \partial_3 b_3 + b_2 \partial_3 a_3 - b_1 \partial_1 a_2 + b_1 \partial_2 a_1 + b_3 \partial_2 a_3 - b_3 \partial_3 a_2 \\ + a_1 \partial_1 b_2 + a_1 \partial_2 b_1 + a_3 \partial_2 b_3 - a_2 \partial_3 b_2 \\ a_3 \partial_1 b_1 + b_3 \partial_1 a_1 + a_3 \partial_2 b_2 + b_3 \partial_2 a_2 + a_3 \partial_3 b_3 + b_3 \partial_3 a_3 - b_1 \partial_1 a_3 - b_2 \partial_2 a_3 + b_1 \partial_3 a_1 - b_2 \partial_3 a_2 \\ - a_1 \partial_1 b_3 - a_2 \partial_2 b_3 + a_1 \partial_3 b_1 - a_2 \partial_3 b_2 \end{pmatrix}$$

$$= \begin{pmatrix} a_1 \partial_1 a_1 b_1 \\ a_1 \partial_2 a_1 b_1 \\ a_1 \partial_3 a_1 b_1 \end{pmatrix} + \begin{pmatrix} b_1 \partial_1 a_1 \\ b_1 \partial_2 a_1 \\ b_1 \partial_3 a_1 \end{pmatrix} = \checkmark$$

$$\vec{v}(\vec{a} \times \vec{b}) = \begin{vmatrix} \sigma_1 a_1 b_2 + \sigma_3 a_1 b_3 - \sigma_2 a_1 a_2 - \sigma_3 b_1 a_3 \\ \sigma_2 a_1 a_2 b_1 + \sigma_3 a_2 b_3 - \sigma_1 a_2 a_1 - \sigma_3 b_2 a_3 \\ \sigma_1 a_3 b_1 + \sigma_2 a_3 b_2 - \sigma_2 b_3 a_2 - \sigma_1 b_3 a_3 \end{vmatrix}; \vec{v}(\dots) = \left(\begin{pmatrix} b_1 a_1 \sigma_1 \\ b_2 a_1 \sigma_1 \\ b_3 a_1 \sigma_1 \end{pmatrix} + \begin{pmatrix} a_1 b_1 \sigma_1 \\ a_2 b_1 \sigma_1 \\ a_3 b_1 \sigma_1 \end{pmatrix} \right) \vec{e} + \dots$$

$$(*) = \delta_1 a_1 b_1 - \delta_1 b_1 a_1 ; \quad (**) = \delta_2 a_2 b_2 - \delta_2 b_2 a_2 ; \quad (***) = \delta_3 a_3 b_3 - \delta_3 b_3 a_3$$

$$b) \quad \vec{\nabla}(\vec{a} \times \vec{b}) = \underbrace{\delta_1(a_2 b_3 - a_3 b_2)}_{\uparrow} + \underbrace{\delta_2(a_3 b_1 - a_1 b_3)}_{\uparrow} + \underbrace{\delta_3(a_1 b_2 - a_2 b_1)}_{\uparrow} + (\dots a \vec{\nabla} b)$$

$$(\dots) = b_1(\delta_2 a_3 - \delta_3 a_2) + b_2(\delta_3 a_1 - \delta_1 a_3) + b_3(\delta_1 a_2 - \delta_2 a_1)$$

$$= -a_1(\delta_2 b_3 - \delta_3 b_2) + a_2(\delta_3 b_1 - \delta_1 b_3) - a_3(\delta_1 b_2 - \delta_2 b_1)$$

$$= \underbrace{\delta_1(-a_3 b_2 + a_2 b_3 + a_2 b_3 - a_3 b_2)}_{\uparrow} + \underbrace{\delta_2(a_3 b_1 + a_3 b_1 - a_1 b_3 - a_1 b_3)}_{\uparrow} + \underbrace{\delta_3(a_1 b_2 + a_1 b_2 - a_2 b_1 - a_2 b_1)}_{\uparrow}$$

$$= (\dots) \cdot \text{[scribble]} \Rightarrow \checkmark$$